

MOBILITY

Mobility Nodes | Boston, MA | Nontraditional
POC: Kevin Diaz | [Email](#) | [Website](#) | [LinkedIn](#)

Q: What is something unique about your product or service?

A: Capability Developer for the Joint Enabling Capability for dismounted warfighters exposed to IED/Mines for in-stride breaching (obstacle reduction) with C2OTM for autonomous reconnaissance (RAS-G IOP).

Q: What capability gaps are you able to fill and which industry colleagues would you like to know about them?

A: He is the creator and originator of Capability Solutions using modular, interoperable and scalable technologies for robotic maneuver systems. His Command and Control technology capability was researched and developed from 2010 to present. The Joint Concept attributes (JCAs/IPLs) are dual use and combine to increase Protection, Situational Awareness and Survivability for the ability to collect operational information given an advanced A2/AD threat environment with sensors, AI and .

Q: How did your organization originate?

A: Kevin Diaz is an American Technology Developer inventing (patents) the Joint Enabling Capability Mobility Nodes. His Operations Research led to Author several Concept of Operations (Copyrighted) defined draft Capability Documents. He is actively pursuing DoD technology transition for the Capability Solution of Mobility Nodes.

Capabilities

C2OTM Survivability Dismounted Maneuver Robotic Platform